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A Summary

of

Proceedings

of the

Department of Defense Robotics Applications Workshop

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Volume I

(Exclusive of Presentations)

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A Summary

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Department of Defense Robotics Applications Workshop

Sierra Inn Sacramento, California

October 4-7, 1983

Volume I

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FOREWORD

The proceedings of the DOD Robotics Applications Workshop contain presentations and summaries of material offered at the workshop. There were 74 formal day presentations, eight roundtable summary presentations, and ten evening presentations offered in the three-day workshop period; in all, more than 46 hours of presentations and discussion.

Not all speakers offered hard copy material of presentation graphics. However, all formal day sessions were audiotaped. Thus, wherever hard copy was not provided, a brief summary of what was offered has been reconstructed from the corresponding audiotape and included in the proceedings. The material submitted by the presenters has generally been reproduced as received, except where the graphic quality of the submittal mandated that minor retyping or enhancement be effected to assure reproduceability.

The proceedings are organized to follow the flow of the workshop. An Executive Summary is provided at the beginning of Volume I and includes: (1) material on the DOD organic industrial base and its operations and processes; (2) a listing of current major DOD industrial robotics projects; and (3) the menus of needs, issues, and project ideas developed by the eight roundtables for the ten technical topic areas. The roundtable menus constitute the primary product of the workshop.

Following the Executive Summary is introductory material describing the genesis of the workshop and its organization. Abstracts of private sector expert briefs and the operations and processes briefs of the DOD activities constitute the balance of Volume I (Presentations 1-18).

Volume II (Presentations 19-47) contains material offered by DOD activities on current robotics projects and plans for the future. Volume III (Presentations 48-74) contains the balance of the DOD current projects/future plans material, the roundtable output summaries, and a list of workshop attendees. Bon appetit!

EXECUTIVE SUMMARY

The DOD Robotics Applications Workshop was held October 4-7, 1983 at the Sierra Inn, Sacramento, California. The event was co-hosted by the Air Force Sacramento Air Logistics Center and the Sacramento chapter of the Society of Logistics Engineers (SOLE). The workshop brought together for the first time private sector experts and engineering and senior management representatives from all the industrial activities of the three services save one (Norfolk Naval Shipyard) to focus on a leading edge industrial technology. This had never been done before. More than two hundred attendees (180 + formal registrants) from army depots and arsenals, navy shipyards, air rework facilities, weapons stations and ordnance activities, supply centers, public work centers, air force logistics centers, the Defense Logistics Agency, DOD, etc., received briefs on the state-of-the-art, current practice, successful implementations, and current research and research directions in robotics from 13 private sector experts chosen by the Robot Institute of America (RIA).

Next, attendess selected by the represented DOD Industrial activities presented the industrial processes and process economics of their industrial operations to the audience. Current robotics projects and project plans for robotics and automation for both the near term and the future were also offered by the attending DOD activities.

Finally, the resultant elevated knowledge base and collective expertise of both the private sector and public sector attendees were applied in three dimensions (current applications, technology transfer/manufacturing technology needs, and research issues and needs) in ten technical topic areas by eight groups of attendees in a unique brainstorming roundtable format. The result was a knowledgeably ranked menu of potential robotics-related investments which represent an extraordinary and stunning opportunity to enhance the productivity, performance, and capability of the Department of Defense organic industrial base over the next decade.

The ten robotics-related technical areas addressed were: (1) Applications; (2) Installation/Design Concepts; (3) Safety and Security; (4) Languages; (5) Controls and Integrated Systems; (6) Mechanical Systems and Precision Operations; (7) Vision Systems; (8) Hands and End Effectors; (9) Sensors; and (10) Transportability/Mobility. That robotics is a systems issue embedded in an automation framework is most apparent because the roundtable-developed menus in these ten technical areas show considerable interaction and overlap. However, a remarkable range of distinct applications, needs, and potential project investments emerged in each technical area, many of which were unique and did not overlap the concepts developed in other roundtables. Each workshop participant was afforded the opportunity to participate in three roundtables of choice, and thus each technical area was brainstormed, discussed and the resultant product rated by three different groups of DOD participants utilizing for each iteration the same private sector expert as leader/facilitator.

Following this narrative is a workshop summary which outlines the needs, issues, and priorities developed by workshop attendees in each of the aforementioned technical areas. The summary is in essence an investment planning guide in robotics and automation systems for the entire DOD in-house industrial base, and should prove to be a valuable resource not only to DOD technology and capital investment planners but also to the robotics industry and academia as they attempt to assess and plan product development, research, and technology transfer (mantech) needs and priorities in support of the DOD organic industrial base.

CONCLUSIONS

- o ROBOTICS IS A SEMINAL DEPOT TECHNOLOGY
- o IDEAL ENVIRONMENT: LABOR INTENSIVE BUSINESS
- o BROADEST POSSIBLE ROBOTICS APPLICATION PANORAMA
- o EXTRAORDINARY POTENTIAL EXISTS FOR CURRENT IMPLEMENTA-TIONS
- o MANY MANTECH PROJECT OPPORTUNITIES
- o MUCH BUSINESS-SPECIFIC R&D NEEDED
- HEAVY SPILLOVER TO PRIVATE SECTOR APPLICATIONS
- NEW ECONOMIC MODELS NEEDED FOR SMART AUTOMATION INVESTMENTS
- o INVESTMENT PLAN INTEGRATED WITH OVERALL MODERNIZATION/ AUTOMATION OBJECTIVES NEEDED
- O DEPOT PROCESS ARCHITECTURE MODEL NEEDED
- o ROBOTICS IS A SYSTEMS ISSUE (AN EMBEDDED TECHNOLOGY)
- o GENERIC APPROACHESTOINTEGRATION OF PROCESS, INTER-FACES, ROBOTICS NEEDED

RECOMMENDATIONS

- o AGGRESSIVELY PURSUE CURRENT INVESTMENT OPPORTUNITIES
- o DEVELOP NEW ECONOMIC JUSTIFICATION MODEL (A LA IBM)
- O DEVELOP COORDINATED TRI-SERVICE ROBOTICS R&D AND MANTECH PLAN
- o AGGRESSIVELY PURSUE ROBOTICS MANTECH INITIATIVES
- O DEVELOP DOD ROBOTICS R&D PROGRAM ELEMENT
- o FUND DOD ROBOTICS R&D INVESTMENT LINE FOR TRI-SERVICE COMPETITION
- O CONSIDER ROBOTICS AS COMPONENT OF OVERALL OVERHAUL, REPAIR, REMANUFACTURING SYSTEM (CIM)
- o INITIATE PROJECT TO MODEL ARCHTYPE OVERHAUL, REPAIR, REMANUFACTURING ARCHITECTURE (HIERARCHICAL CONTROL)
- o INITIATE DECADE-LONG PLAN TO IMPLEMENT HIERACHICAL CON-TROL AUTOMATION ARCHITECTURE IN DOD DEPOTS
- O SOLICIT/INVOKE SUPPORT OF THE CONGRESS FOR JOINT INDUSTRY/ACADEMIA/DOD ROBOTICS/AUTOMATION INVESTMENT ALLIANCE
- O USE DOD ROBOTICS WORKSHOP PROCEEDINGS AS REFERENCE PLANNING GUIDE FOR DOD ROBOTICS PROGRAM

THE DOD ORGANIC INDUSTRIAL BASE

- o AIR INDUSTRIAL ACTIVITIES
- o PRODUCTION ARSENALS
- o PRODUCT LINE DEPOTS
- o SHIPYARDS
- o WEAPONS STATIONS/ORDANCE ACTIVITIES
- o SUPPLY CENTERS
- MAINTENANCE/PUBLICK WORKS CENTERS
- o LABORATORIES WITH PRODUCTION/SUPPORT OPERATIONS

THE BUSINESS

- o VOLUME: \$10B/YEAR
- o OVERHAUL
- o REPAIR
- o REMANUFACTURING
- o MANUFACTURING (ORDNANCE)
- o ENGINEERING/TECHNICAL SERVICES
- o SUPPLY SUPPORT
- o FACILITY MAINTENANCE AND SUPPORT

THE PRODUCTS

- o TACTICAL VEHICLES
- o AIRCRAFT
- o SHIPS
- O WEAPONS SYSTEMS
- O ORDNANCE AND ORDNANCE SYSTEMS
- O SUPPORT EQUIPMENT AND SYSTEMS
- O SPARES AND PIECE PARTS
- O TECHNICAL SERVICES AND DATA
- O COMMUNICATIONS/ELECTRONICS
- O SUPPLY INVENTORY/PERSONNEL ASSETS
- o MISSILES

THE ORGANIZATION

- O PROCUREMENT/SUPPLY
- O PRODUCTION PLANNING AND CONTROL
- o TRANSPORTATION
- o PRODUCTION
- o ENGINEERING
- O QUALITY ASSURANCE
- O FINANCIAL AND COMPTROLLER
- O ADMINISTRATIVE SERVICES
- O TEST AND SELLOFF
- O PACKAGING AND PRESERVATION
- O MEASUREMENT AND STANDARDS

TYPICAL DOD DEPOT PROCESSES

MATERIAL HANDLING/STORAGE MATERIAL TRANSFER/LOADING/UNLOADING 0 PALLETIZING 0 MACHINE LOADING 0 FORGING 0 DIE CASTING 0 INVESTMENT CASTING 0 0 MOLDING METAL FABRICATION/MACHINING 0 DISASSEMBLY 0 **ASSEMBLY** 0 CIRCUIT BOARD HANDLING 0 ELECTRONIC COMPONENT INSERTION 0 WIRE HARNESS MANUFACTURE 0 DRILLING/ROUTING 0 CUTTING/BURNING 0 TESTING, MECHANICAL 0 TESTING, ELECTRONIC 0 WELDING 0 JOINING 0 PAINTING 0 COATING 0 FACING/HARDENING/TREATING 0 INSPECTION 0 **PACKAGING** 0 MATERIAL APPLICATION 0 COMPOSITE LAYOUT 0 **DELIVERY** 0 SORTING 0 **CLEANING** 0 SECURITY 0 TOOL CONTROL 0 ANTHROPOMORPHIC EQUIPMENT OPERATION 0

OTHER

CURRENT/PLANNED DEPOT ROBOTICS PROJECTS

PROJECT	SERVICE
TURBINE BLADE REPAIR	AIR FORCE
PLASMA SPRAY	AIR FORCE
FINISHING	AIR FORCE
HONEYCOMB SHAPING	AIR FORCE
SAND BLASTING/CLEANING	AIR FORCE
REAL TIME X-RAY	AIR FORCE
LASER PAINT REMOVAL	AIR FORCE/NAVY
ROBOTIC PAINTING	AIR FORCE/NAVY/ARMY
RIVETING/DERIVETING	NAVY
WIRE HARNESS MANUFACTURE	NAVY
NEUTRON RADIOGRAPHY INSPECTION	NAVY
SEAM WELDING/CUTTING	NAVY
SMALL STRUCTURE WELDING	NAVY/ARMY
VEHICLE SUSPENSION/TRACK DISASSEMBLY	ARMY
SHELTER REFINISHING	ARMY
VAN ASSEMBLY	ARMY
HAZARDOUS MATERIALS HANDLING	ARMY

ROUNDTABLE TOPICS

- o APPLICATIONS
- o INSTALLATION/DESIGN CONCEPTS
- o SAFETY AND SECURITY
- O LANGUAGES
- o CONTROLS AND INTEGRATED SYSTEMS
- o MECHANICAL SYSTEMS/PRECISION OPERATIONS
- o VISION SYSTEMS
- O HANDS AND END EFFECTORS
- o SENSORS
- o TRANSPORTABILITY/MOBILITY

PRIVATE SECTOR PRINCIPALS

0	VERN ESTES (G.E.)	APPLICATIONS
0	DAVID ANDERSON (FORD)	APPLICATIONS
0	RICHARD HOHN (CINCINNATI	INSTALLATION/DESIGN
	MILLICRON)	CONCEPTS, SAFETY/
		SECURITY
0	ROBERT TROUTEAUD (ROBOT	INSTALLATION/DESIGN
	SYSTEMS, INC.)	CONCEPTS, SAFETY/
		SECURITY
a	ROGER NAGEL (LEHIGH UNIV.)	LANGUAGES, CONTROLS
-		INTEGRATED SYSTEMS
0	JOHN EVANS (NOVA ROBOTICS)	LANGUAGES, CONTROLS,
•		INTEGRATED SYSTEMS
0	DELBERT TESAR (UNIV. OF	•
•	FLORIDA)	PRECISION OPERATIONS
0	HOWARD STERN (ROBOTIC	VISION SYSTEMS
•	SYSTEMS, INC.)	
0	RONALD HILLS (GENERAL	HANDS AND END EFFECTORS
	DYNAMICS)	
0	VICTOR SCHEINMAN	SENSORS
	(AUTOMATIX)	
0	MICHAEL KNASEL	TRANSPORTABILITY/MOBILITY
•	(SAI, INC.)	
	· · · · · · · · · · · · · · · · · · ·	

APPLICATIONS - SESSIONS 1 & 2

- 1. PAINT/DEPAINT
- 2. INSPECTION
- 3. X-RAY INSPECTION
- 4. MIG/TIG LASER WELDING
- 5. RIVET/DERIVET
- 6. ASSEMBLY/DISASSEMBLY
- 7. WIRE HARNESS ASSEMBLY
- 8. FIRE FIGHTING
- 9. COMPOSITE LAY-UP
- 10. GUN LOADING

UNRANKED APPLICATIONS - SESSIONS 1 & 2

- o STENCILING, MARKING
- o SHOT PEENING
- o DEBURRING
- o CLEANING
- o MIXING
- o BOX FABRICATION
- NATER JET CUTTING
- o PACKAGING

APPLICATIONS - SESSION 3

- 1. PAINT/DEPAINT
- 2. GRIT BLAST
- 3. DEMENSIONAL INSPECTION
- 4. X-RAY INSPECTION
- 5. MIG/TIG, LASER WELDING
- 6. RIVET/DERIVET
- 7. ASSEMBLY/DISASSEMBLY
- 8. THERMO/PLASMA SPRAY
- 9. CALIBRATION/TEST
- 10. PACK, DEPACK, PALLETIZING

APPLICATIONS - GENERAL COMMENTS

- o ECONOMIC JUSTIFICATION DIFFICULT
 - o ANS: MULTIPLE USE/APPLICATIONS
- O ELECTRONIC REPAIR UNIVERSAL ROBOTICS NEED
- O ROBOTICS PRECISION PARTS HANDLING -UNIVERSAL NEED
- O PARTS DESIGNED FOR AUTOMATION -UNIVERSAL NEED
- o HIGH MOBILITY ROBOTICS UNIVERSAL NEED

INSTALLATION/DESIGN CONCEPTS AND SAFETY/SECURITY

- VENDOR CHOICE CRITERIA
- o PRE AND POST INSTALLATION TRAINING
- INTERFACE WITH OLDER EQUIPMENT
- o HUMAN FACTORS
- O CRITERIA FOR TURN KEY SYSTEMS
- o FEEDING MECHANISMS TO ROBOT
- o ROBOT LAY-OUT
- O ROBOT SERVICE, LIFE-HOSTILE ENVIRONMENT
- o CAD/CAM, ATE, INSPECTION INTERFACE
- o FLEXIBILITY FOR SMALL BATCH
- o ADVANCE SENSOR INTERFACING
- o WAREHOUSING AUTOMATION
- o EXPLOSION PROOFING
- o MOBILITY, POWER
- O NEW MECHANICAL ROBOT DESIGN
- SENSOR INTERFACING
- o HUMAN SAFETY
- o PART/MACHINE SAFETY
- O PAINTING/STRIPPING CELL--SMALL PARTS
- O SYSTEM MAINTAINABILITY
- o DERIVETING
- o MULTI-USE SYSTEMS
- o LOW VOLUME INSPECTION

INSTALLATION/DESIGN CONCEPTS AND SAFETY/SECURITY (CON'T)

- o FUEL/MANIFOLD ASSEMBLY
- O LARGE PAINTING/STRIPPING CELL
- o ROBOT SYSTEMS APPROACHES
- o PLATING CELL
- O BRAKE SHOE CELL
- o FOAM-IN-PLACE PACKAGING
- o VEHICLE/TRUCK ASSEMBLY
- MANUFACTURING OF WOOD SHIPPING CONTAINERS
- o BEARING INSPECTION/MATCHING
- O BLACK AND VANE CELL SYSTEM
- o ROBOTIC INTERIOR/CONTAINER COATING
- o KITTING
- O CIRCUIT BOARD TESTING/REPAIR SYSTEMS
- o SURFACE MEASUREMENT
- o SMALL SHIPBOARD ROBOTICS SYSTEMS
- O SYSTEMS CONTROL INTERFACES
- o GUIDELINES FOR SYSTEMS SPECIFICATIONS
- ROBOTICS SECURITY/SAFETY DESIGN CONCEPTS
- O INTEGRATED SYSTEM DESIGN: MIS, FMS, CIM
- o SOLDER/DESOLDER SYSTEM
- O OPERATING ENVIRONMENT SPECIFICATION
- o AUTOMATED NDI/TEST
- O PIPE PREP, WELD, NDT
- o INTERIOR TANK PORTABLE SERVICE ROBOTICS
- O CO-ORDINATED MULTI-ARM ROBOT SYSTEMS
- o STANDARDIZED SOFTWARE

LANGUAGES, CONTROLS, INTEGRATED SYSTEMS PROCESS - TECHNOLOGY MATCHES

- 1. LOAD MACHINE WITH MOVING TURNTABLE (EXPLOSIVE)
- 2. ADAPTIVE PROCESS APPLICATIONS (WELDING, PAINTING, GRINDING)
- 3. MOVE BOXES WITH VARIABLE DIMENSIONS
- 4. ENGINE PARTS PAINTING
- 5. ENGINE PARTS INSPECTION
- 6. GAUGE BLOCK CALIBRATION
- 7. MACHINE TENDING -NC CELLS
- 8. BLASTING OF SIMPLE SURFACES
- 9. PAINTING SIMPLE PREDICTABLE GEOMETRIES
- 10. BEARING INSPECTION SIMPLE ACCEPTANCE CRITERIA
- 11. INSTRUMENT SOLDERING AND DESOLDERING SIMPLE MANUFACTURING TECHNOLOGY NEEDS

1. MOVE BOXES WITH HIGHLY VARIABLE DIMENSIONS

- 2. DISASSEMBLY OF SIMPLE ELECTRONICS PACKAGES/DEVICES
- 3. BLASTING OF IRREGULAR SURFACES WITH CONSTRAINTS (AVOID NAME PLATES)
- 4. DISASSEMBLY AND CLEANING OF FUEL MANIFOLD NOZZLES
- 5. PAINTING COMPLEX SURFACES, COLORS, PATTERNS
- 6. BEARING INSPECTION AND CLEANING MULTIPLE ACCEPTANCE CRITERIA
- 7. INSTRUMENT SOLDERING AND DESOLDERING COMPLEX
- 8. WHOLE AIRCRAFT PAINTING/MARKING
- 9. SURFACE INSPECTION AND DEFECT MARKING
- 10. REPAIR OF COMPOSITES
- 11. INTEGRATED INSPECTION, DATA STORAGE SYSTEM
- 12. NEUTRON RADIOGRAPHY CONTROLS
- 13. LASER PAINT STRIPPING CONTROLS
- 14. CONFORMAL COATING REMOVAL
- 15. CONTROL/PROGRAMMING FOR LOW VOLUME PLASMA COATING
- 16. INTEGRATION OF COMPLEX SENSORS AND VISION WITH ROBOT CONTROL
- 17. STANDARDIZED PROGRAMMING TECHNOLOGY
- 18. INTEGRATED CAD/CAM DATA ROBOTICS SYSTEMS
- 19. GROUP TECHNOLOGY PROCESS PLANNING DATA INTEGRATION
- 20. STANDARD INTERFACES TO SENSORS, DATA BASES, ETC.
- 21. SMALL PARTS NDI
- 22. GENERAL PURPOSE CIRCUIT BOARD SCREENING

LANGUAGES, CONTROLS, INTEGRATED SYSTEMS (CON'T) R&D NEEDS

- 1. DISASSEMBLY OF COMPLEX PACKAGES/DEVICES
- 2. ASRS BIN/ITEM PICKING
- 3. SHEET METAL FABRICATION, CUTTING, CENDING VIA CAD/CAM LINKS
- 4. WHOLE AIRCRAFT PAINTING/DEPAINTING
- 5. MAN-MACHINE GENERIC CONTROL SYSTEM FOR FIELD APPLICATIONS
- 6. COMPOSITES REPAIR
- 7. INTEGRATED INSPECTION DATA/MACHINE TOOL DRIVER SYSTEM
- 8. INTEGRATION OF ROBOT VISION WITH CONTROL
- 9. TASK PROGRAMMING WITH MAN-MACHINE INTERFACE (SHOP FLOOR)
- 10. FUNCTIONAL PROGRAMMING
- 11. GROUP TECHNOLOGY INTERFACE
- 12. CO-ORDINATED CONTROL OF MULTIPLE ROBOTIC DEVICES

SUMMARY R&D NEEDS

- o REQUIREMENTS DEFINITION AND STANDARD PROGRAM METHODOLOGY
- O COMMUNICATION STANDARDS BETWEEN ROBOT CONTROL AND SUPERVISORY CONTROL (STD. INTERFACES)
- O THREE DIMENSIONAL IGES DEVELOPMENT

MECHANICAL SYSTEMS/PRECISION OPERATIONS

----RATIM6S----

			RED
	R 01	MANTECH	LEVEL REQUIRED
MEED/OPERATION	VALUE VALUE	AVAILABILITY	(AVAIL)
PRECISION WELDING AND GRINDING (TURBINE BLADES)	٤	-	10(0)
PRECISION INSPECTION AND QUALITY MEASUREMENT	2	2	(4)9
PRECISION DRILLING OF STRUCTURES	7	5	9(1)
DERIVITING/RIVETING	5	9	8(2)
MECHANICAL ASSY/DISASSY	-	ħ	1(9)
HAZARDOUS OPERATIONS/MUNITIONS	9	3	2(5)
PRECISION ROUTING/TRIMMING (AIRFRAME SURFACE PANELS)	7	∞	7(3)
SURFACE PATCHING FOR COMPOSITE STRUCTURES AND HONEYCOMB PANELS	6	7	۴(9)
AVIONICS/ELECTRONICS MODULE MAINTENANCE	∞	o	3(7)
NUCLEAR REACTOR MAINTENANCE	10	10	2(8)

APPLICATIONS

- o RECEIVING-BOX SIZE
- o INVENTORY
- o SEWER INSPECTION
- O SEAM TRACKING-IRREGULAR SHAPES ALUMINUM
- o SMALL PARTS INSPECTION
- o AIRCRAFT SURFACE INSPECTION
- o SMALL PARTS ASSEMBLY
- O PART MEASUREMENT
- o PACKAGING
- o PROFILE
- o PALLETIZING
- LOAD/UNLOAD CAROUSEL CONVEYORS
- o PARTS/DIMENSION REPLICATION
- o ORDER PICKING
- O LARGE PART LOCATION AND SUBFEATURES
- o BAR CODE LOCATION/OPERATIONS
- o BIN PICKING
- o PC BOARD INSPECTION
- o COLOR IDENTIFICATION

VISION SYSTEMS (CON'T)

MANTECH NEEDS

- o INSPECTION OF VERY LARGE OBJECTS
- o CONTINUOUS WELDING
- o SMALL COMPONENTS INSPECTION
- O DERIVETING/FASTENER REMOVAL
- o TOOL GUIDANCE
- o FASTENER LOCATION
- o WEAPON LOADING
- o FIRE FIGHTING
- O AIRCRAFT COMPONENT ASSEMBLY
- o GMA WELDING
- O REAL TIME VISUAL DATA ACQUISITION
- o PART IDENTIFICATION

VISION SYSTEMS (CON'T)

R&D NEEDS

- o SORTING (COMPLEX GEOMETRIES)
- o WELDING
- o FASTENER IDENTIFICATION
- o CONTOUR FOLLOWING (FOR PAINTING, CORE REPAIR)
- O INSPECTION FOR DISASSEMBLY/ASSEMBLY
- o PRECISION INSPECTION
- o MACHINE LOADING
- o LOADING TOOL CHANGING
- o BAR CODE OPERATIONS
- O SURFACE QUALITY AND PREPARATION
- o PATTERN ASSEMBLY
- o MAGNAFLUX INSPECTION
- o PART RECOGNITION
- o SAFETY AND SECURITY SYSTEMS
- o 3D REPLICATION (PARTS ON DEMAND)

POTENTIAL APPLICATION

067	₹
ECHNOLOGY	VISIO
LENT T	BINARY
	20 1

2D GRAY SCALE VISION

3D (DOT-LINE SENSOR)

3D (PLANER-CCD CAMERA)

GRINDING, DRILLING, PARTS MFG., MOBILE ROBOT

GRINDING, DRILLING, ETC.

3D (STEREO)
3D (MULTIPLE PLANES)

LIMITATIONS AMBIGUITY SURFACE REFLECTANCE

AMBIGUITY

DAYLIGHT, SHADOWING

DAYLIGHT, SHADOWING

COMPUTATIONALLY INTENSIVE

DAYLIGHT, SHADOWING

AS ABOVE; MOBILE ROBOT

CURRENT TECHNOLOGY 2D BINARY VISION 2D GRAY SCALE VISION	APPLICATION AREA INSPECTION, MEASUREMENT DITTO	SPECIFIC APPLICATION SORTING, ASSEMBLY DITTO, PLUS BIN PICKING
3D (DOT-LINE SENSOR)	DEPTH GAGING AND CONTOUR	SCANNING
3D (PLANER-CCD CAMERA)	CONTOURING	MEASUREMENT, WELD TRACKING, INSPECTION
3D (STEREO)	MEASUREMENT	MAPPING, INSPECTION
3D (MULTIPLE PLANES)	SURFACE MEASUREMENT	COPYING, INSPECTION, MEASUREMENT

CURRENT RESEARCH

- O COLLISION AVOIDANCE
- O GEOMETRIC REASONING
- O PLANNING AND STRATEGIES
- o RECOGNITION
- O APPLICATIONS OF 3D VISION
 - O INSPECTION/MEASUREMENT
 - O WIRE HARNESSING
 - o GRINDING
 - o WELDING
 - O MATERIAL HANDLING
 - O ASSEMBLY/DISASSEMBLY
 - O DRILLING/ROUTING

HANDS AND END EFFECTORS

PROCESS APPLICATIONS

- 1. MATERIALS HANDLING 9. GRINDING 2. MACHINE LOAD 10. CUTTING INSPECTION 3. WELDING 11. PAINTING DISASSEMBLY 4. 12. 13. STRIPPING/DEPOSITING ASSEMBLY 5. 6. CLEANING/BLASTING 14. DEBURRING METAL SPRAY 15. MASKING 7.
- 8. SHOT PEENING

MANTECH NEEDS

- 1. ASSEMBLY/DISASSEMBLY (COMPONENTS)
- 2. WIRE HARNESS ASSEMBLY
- 3. INSPECTION/GAGING
- 4. MARKING/ENGRAVING (LASER/OTHER)
- 5. LASER WELDING
- 6. MATERIAL APPLICATION

R&D NEEDS

- 1. ASSEMBLY/DISASSEMBLY (LARGE AND SMALL ITEMS)
- 2. WIRE HARNESS ASSEMBLY
- 3. AUGMENTED END EFFECTOR STRUCTURES
 - o VISION AUGMENTED
 - o TACTILE AUGMENTATION
 - o ADAPTIVE MECHANISMS
 - o LASER INTEGRATION
- 4. UNIVERSAL AND FLEXIBLE STRUCTURES
- 5. MULTIHAND STRUCTURES (AND INTEGRATED CONTROL SYSTEMS)

SENSOR SYSTEMS

PROCESS APPLICATIONS

- o AUTOMATED NDI
- o WELDING
 - o SEAM TRACKING
 - o WELD QUALITY
- o ASSEMBLY/DISASSEMBLY
 - O CLOSE TOLERANCE PARTS
 - o INCIPIENT DAMAGE
 - o INSPECTION AND REPAIR
- O BIN PICKING AND SORTING
- o PACKAGING
 - SELECTING METHOD, ORIENTATION, ETC.
- o RIVETING/DERIVETING
 - o MATERIAL
 - o TYPE
- o PAINTING
 - o SURFACE TRACKING
 - o SURFACE FEATURES
- O NON-CONTACT 3D GAGING
- o GRINDING AND POLISHING
- O SOLDERING/DESOLDERING
 - O PRESENCE OF SOLDER
 - o FLUID DISPENSE VERIFICATION
- o SECURITY SYSTEM INTRUSION
- o PWB ASSEMBLY
- o CHEMICAL/PHYSICAL MIXING
- o FUEL LEAK DETECTION

SENSOR SYSTEMS

MANTECH NEEDS

- o GENERIC SENSOR INTERFACES
- O NDI SENSORS FOR ROBOTS (ALL TYPES)
- o INTEGRITY SENSOR
- O TACTILE MATERIAL HANDLING SENSORS
- O REAL TIME WELD PARAMETRIC SENSORS
- O COMPOSITE MATERIAL COMPOSITION SENSOR
- O FUEL LEAK DETECTION FOR ROBOT APPLICATION

R&D NEEDS

- o HOLOGRAPHIC PARTS ID
- o FAST MATERIAL COMPOSITION ANALYSIS
- O INTEGRATED FLOW DETECTION AND REPAIR CAPABILITY
- o TASK-SPECIFIC SENSORS
- O INTEGRATED SENSOR SYSTEMS
- O ENABLING SENSOR DEVELOPMENTS

TRANSPORTABILITY AND MOBILITY

APPLICATIONS

- o PAINTING
- o WELDING
- o SANDING/BLASTING
- o MULTI-STATION SYSTEMS
- o AMMUNITION HANDLING
- O NUCLEAR HARDENING
- o FIREFIGHTING
- O ORDNANCE LOADING/UNLOADING
- o FLEXIBLE MACHINING/MFG SYSTEMS
- O CHEMICAL CLEANUP/CLEANING
- LARGE STRUCTURE MECHANICS
 - o INSPECTION/TEST
 - o PROCESS-WELDING, CUTTING, COATING, ETC.
- o STRIPPING
- o STORAGE AND RETRIEVAL
- o FUELING/DEFUELING
- o PLATING
- o AIRCRAFT TOWING
- o ELECTRONICS TESTING
- o AIRCRAFT RIVETING/DERIVETING
- o ORDNANCE DISPOSAL
- o MOBILE SCAFFOLDING
- o EXPLOSIVES MIXING
- o CUTTING
- o PATCHING AND REPAIR
- o TOOL STORAGE/RETRIEVAL
- o METAL SPRAYING/COATINGS

TRANSPORTABILITY AND MOBILITY

MANTECH NEEDS

- o PAINTING/STRIPPING
- o ELECTRONICS TESTING
- O RIVETING/DERIVETING
- O TANK CLEANING
- o LIGHTWEIGHT ROBOTIC STRUCTURES
- o MODULARITY/MAINTAINABILITY/SERVICEABILITY TECHNIQUES
- O STRUCTURAL LOADING INTERFACES

R&D ISSUES

- o MULTIFUNCTIONAL SYSTEMS
- o MULTI-MEDIA MOBILITY (TRACK, WHEEL, LEG, PROP, ETC.)
- o MULTI-APPENDAGE SYSTEMS (AND CONTROLS)
- o FUEL CELL/HIGH POWER DENSITY PACKAGES
- o POWER TRANSMISSION SYSTEMS
- O ON-BOARD NAVIGATION SYSTEMS
- o STABILITY AIDS/SYSTEMS
- O NUCLEAR HARDENING
- O ON-BOARD INTELLIGENCE
- O ENVIRONMENTAL ADAPTABILITY
- o FAIL-SOFT STRUCTURES
- o HIGH LOAD CAPACITIES (2 TONS)

THE DOD ROBOTICS APPLICATIONS WORKSHOP

October 4-7 1983

Sacramento, California

305.1905.005

INTRODUCTION

The extraordinary pace of recent technology development and application in factory automation and robotics coupled with the pressing need to modernize and increase the productivity and performance of scarce resources in the organic industrial base of the Army, Navy, and Air Force led to the tri-service decision to conduct a DOD Depot Robotics Application Workshop Oct 4-7 1983, in Sacramento, California. This landmark event for the first time brought together - in a structured way-leading edge robotics practitioners possessing a proven track record of implementation successes in the private sector, and the Air Force, Army, and Navy depot personnel responsible for conception, planning, management, execution, and utilization of modernization and productivity enhancement projects.

The workshop represented a rare and never before achieved synergism of the entire in-house industrial base of the three services, focused on a single technology and its applications. The compelling scope, breadth, and depth of DOD organic industrial operations as revealed in the workshop presentations brought home to attendees a realization of the exceptional value and importance of this extraordinary industrial complex to the Department of Defense and the United States.

The workshop surfaced great interest and intent in Robotics and the instruments of automation because the current DOD depot, arsenal, shipyard, ordnance and supply, and aeronautical rework activity annual investment in direct touch labor is very large. The DOD Aeronautical Depots alone expended more than 82M direct manhours in FY 83 in in-house remanufacturing, maintenance, and repair of aeronautical weapon systems and associated products. Approximately one-half of this substantial investment was in the production of components, where direct touch labor is the dominant cost factor. Existing weapon systems acquisition plans and programs, if carried to reasonable percentage of execution, promise to further stress the current DOD work force and physical plant and its capacity to efficiently produce products in support of service operations. The application of labor-saving technology is thus seen as a mandatory adjunct to the continuing effort by service activities to improve performance and the utilization of limited plant, equipment, capital, and human resources.

Modernization of these precious and invaluable resources should hold an uncompromised priority in any balanced defense program. Too often, however, investments in the DOD in-house industrial complex are delayed or rejected in favor of investment in the weapons and products the DOD activities are chartered to support. The result is inevitably a continuing and burdensome growth in the life cycle cost of ownership of DOD assets, a corresponding decrease in the portion of the DOD dollar available for new weapon and military asset acquisition, and an ongoing deterioration in the overall vitality and efficiency of the service-organic industrial complex. Perhaps a Robotics and Automation pool of dedicated fiscal resources held, administered, and replenished at the DOD level and meritoriously competed on a project basis by the three services is what is required to insure that erosion of investment intent does not occur.

In any event, it is certain that aggressive and persistant long-term direction and action by the Congress and the Department of Defense are necessary to insure that the three services plan and vigorously implement a modernization program with short, mid, and long term components of capital-investment, technology transfer (mantech) and manufacturing research. The investment menu surfaced by the DOD Robotics

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Applications Workshop represents an exceptional opportunity to appropriately dedicate fiscal resources to achieve specific, meaningful productivity and performance enhancement of the DOD in-house industrial base.

The workshop was structured as follows: (1) Private sector experts selected by The Robot Institute of America (RIA) conducted state-of-the-art Briefs on Robotics and Automation systems; (2) representatives of all the DOD industrial activities of the three services save one (Norfolk Naval Shipyard did not attend) presented briefs on their industrial processes and operations, process economics, current robotics projects, and plans for the future; and (3) brainstorming roundtables led by experts from private industry and staffed by DOD attendees took advantage of the enhancement and synergism effected by (1) and (2) to discuss and generate menus of needs and investment opportunities in current applications, technology transfer, and research for ten robotics-related technical areas. A multi-media evening program was included to facilitate total immersion in the technology of interest.

The benefits derived from the workshop were many. They included: (1) the opportunity for DOD industrial depot personnel to receive information on successful robotics techniques and applications now occurring in the private sector and at other DOD depots; (2) the opportunity for depot personnel to receive state-of-the-art briefs on current technology and a timetable on new developments in the robotics field; (3) the chance for participants to compare production problems, plans, and needs with other depot professionals in a structured exchange and problem solving environment; (4) a rare chance for attendees to influence the thrust and direction of a proposed manufacturing technology and applied research initiative - to be undertaken within the existing programmatic framework of the three services - whose purpose is to directly address both generic needs and specific application opportunities for robotics and allied automation technology in the service industrial depots; and (5) a unique chance for both depot and selected private sector invitees to be exposed to the process and application areas of our valuable in-house industrial complex, to the end of providing both the understanding of these capabilities and the stimulation to research, develop, and apply nuances of robotics and automation technology to industrial operations heretofore not considered for such an application. The workshop proved to be classically effective in terms of its direct and immediate benefit to participating DOD activities in their equipment, technology, and modernization planning and acquisition efforts. Further, it is believed that the participants' enhanced knowledge and understanding of a fountainhead automation technology will yield enduring long-term benefit to the production posture of the participating service organizations.

The workshop brought a mix of private sector principals from academia, the user community, original equipment manufacturers, turn-key systems houses, and consultant organizations to interact with DOD engineers and managers responsible for technical implementation and resource allocation decisions. The result was both a phenomenal growth in knowledge and understanding by all of both robotics technology and the activities of the DOD industrial base. From these interactions it became apparent to many attendees that many of the issues and developments of interest to the DOD industrial activities possess the potential for applicability in the market-place. Thus, investments made in project opportunities surfaced by the workshop could ultimately provide significant leverage on the competitive posture of the U.S. robotics industry worldwide. The existence of this beneficial multiplier would seem to provide further impetus for prompt and sustained action by the DOD to pursue the investment menu in robotics research and technology developed by the workshop.

DOD ROBOTICS WORKSHOP CONCEPT

- Initiated by MTAG CAD/CAM and metals subcommittees
- All segments \$10B/yr organic base
- · Industrial process emphasis
- Service-private sector information exchange
- RIA-managed industry participation
- Goal: Investment opportunity identification
 - Current applications
 - MANTECH
 - · R&D
- Goal: Enhanced tri-service industrial base technology emphasis
- Goal: DOD sponsored tri-service depot focused technology investment program

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WORKSHOP STRUCTURE

- Robotics briefs (RIA)
 - State of the art
 - Current installations/experience
 - The future: projections
- The DOD organic industrial base
 - Basic processes/technologies
 - Process economics
 - Current robotics/automation installations
 - Planned/future applications
- Roundtables
 - Ten related topics
 - Eight roundtables
 - Three sessions/topics
 - · Led by private sector
 - Roundtable products
 - Process-technology matches (current)
 - MANTECH depot robotics needs
 - Depot robotics research needs

DOD ROBOTICS WORKSHOP

Evenine Program Affilletion "A CAM Update" 4 Oct er Scheinmen Autometix, inc. Cineinnetti MILACRON "Applied Rebotics" 4 Oct Cineinnetti MILACRON "Applied Robotics" 4 Oct Cincinnetti MILACRON "Applied Rebotics" B. Whetsel 4 Oct General Electric Vern Betes "Robot Applications" 4 Oct "Rebet Applications" Tem Hildick Dept of Energy 4 Oet Lehigh University "New Manufacturing Systems" 5 Oct **Recer Negal** Pertamouth Navy Yard "Production Line Concept for 8 Oct Overhouting Submarines" **NOVA Rebettee** 5 Oct John Brans "Rebettee Applications" 5 Oct Ford Motor Company

ROBOTICS APPLICATION WORKSHOP STAFF

SERVICE CHAIRS:

ARMY:

AIRFORCE:

NAVY:

ROBERT HELLEM, IBEA, DRXIB-MM

LAZLO HARY, HQ AFLC/MAXT

FORREST GALE, DSMC (HQ NAVMAT)

DOD ROBOTICS APPLICATION

WORKSHOP CHAIRMAN:

WILLIAM WALDEN, SM-ALC/MAW

PRESIDENT OF SOLE:

SUE O'NEIL, SM-ALC/MMI

FINANCE MONITOR OF SOLE:

MARILYN MILLER, SM-ALC/MMK

FINANCE MONITOR OF MA:

PAT DWYER, SM-ALC/MAW

ACCOMMODATIONS PLANNER:

KAREN HARPER, SM-ALC/MAW

AUDIO-VISUAL AND PUBLICATIONS:

GEORGE ANDERSON, SM-ALC/MAA

MIKE CHANDLER, SM-ALC/MAA

BETTY HOYT, SM-ALC/MAA

DON HAMMERSTEN, SM-ALC/MAA KEITH DANKERTSEN, SM-ALC/MAW

PROTOCOL:

SHEILA MCFALL, SM-ALC/MAA

MARSHA WALLACE, SM-ALC/MAA

ADMINISTRATIVE ASSISTANT:

EDNITA R. OVERSTREET, SM-ALC/MAW

A company

Presentation Subject Overview

The objective in a data matrix prepared for presentation at the DoD Depot Robotics Workshop is to provide the maximum amount of procedural, economic, and technical information possible in-as compressed and summary a format as possible. The basic subjects to be presented by the DoD activities are:

- Industrial Processes/Sequences
 White Collar (staff) Processes
- 3. Current Robotics Projects
- 4. Planned Robotics Projects
- 5. Potential Robotics Projects

The basic subjects to be presented by the private sector invitees are:

- Robotics Overview
 - What are robot systems, parameters, specifications, etc.
 - 2. Current applications
 - 3. What robots can do
 - 4. Limitations/caveats and "experiences."
 - 5. State-of-the-art: What is new and what is coming soon.
 - 6. Current research and development efforts
 - 7. A view of the future: Total systems integration.
- Robotics Project Mini-Tutorial
 - Robotics application assessment
 - 2. Robot cost/pay back analysis
 - Robot investment decision analysis
 - Robot implementation
 - System installation/checkout 2.
 - System integration b.
 - etc.
 - Robot life cycle support
 - a. Maintenance (Hardware)
 - b. Training/work force program
 - Software support/maintenance C.
 - d. Technical data
 - etc.

DOD ROBOTICS APPLICATION WORKSHOP

Presentors and Participant Guide

Presentors:

- 1. All private sector presentations will be free of marketing or sales effort; the goal is maximum transfer of technical information to participants.
- 2. All presentations are to be developed utilizing either vu-graphs or 35/42mm slides.
- 3. Hard copies of all presentation material must be provided to the workshop coordinator prior to September 1 so it can be used in assembling a workshop handbook.
- 4. All presentations are to be as detailed as possible in the time allotted. Depot presentations on process detail should include: (a) process name; (b) a chart of a typical process sequence; (c) touch labor operations should be noted for emphasis; and (d) the economic significance of the process should be noted (i.e., number of units, labor hours per current unit of output, most costly operations in the sequence, hazardous or unpleasant environmental conditions, etc.).
- 5. Summary and matrix charts are to be used whenever possible to compress information.

Participants:

1. You must prepare for this workshop. If you are from a depot, you must be prepared to discuss the following:

(a) the principal industrial processes at your activity;

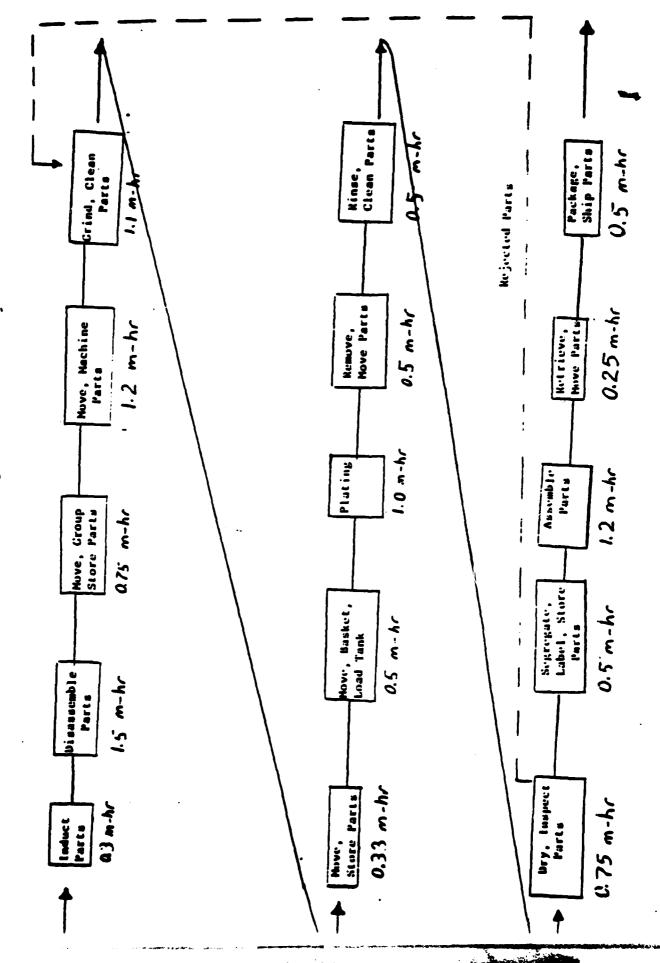
(b) the basic process sequences; (c) the economic significance (ranking) of same; (d) the business volume for each process now and as projected for the mid-term (3 years) horizon; (e) the extent of touch labor in the current process; (f) modernization plans (if any) for your activity, and their potential effect on the principal industrial process sequences at your activity; (g) current and planned robotics projects at your activity, including both technical and administrative project detail; and (h) the projected future process and technology needs of your depot, based on the best available workload projections.

SAMPLE PROCESS INFORMATION MATRIX FORMAT

Process	Touch Labor Braive G	Total	Hazardous/ Unpleasant work env.	Labor Skill Required	Job	Key OPN's Common to other Processes
Welding	50	1,500	705	high	2 yr appr.	yes
Metal Cutting/ Forming	42	1,260	yes	Mod-high	4 yr appr.	yes
Electrical Test	193	5,700	20	high	4 yr appr.	yes
Dissassembly	960	28,500	r. ɔ	low	l yr trng.	yes
Assembly	1,520	30.600		high	4 yr appr.	yes .
Material Handling	955	2ē,650	r.e	low	3-6 month OJT	yes
Material "ement/ ting	292	8,760	r.ə	low	3 month OJT	yes
Packaging'	112	3,360	c.3	рош	l yr trng. and OJT	yes
Material Storage/ Retrieval	60	1,800	ca	low	6 month trng. and OJT	no
Parts Cleaning	27	810	yes	low	3 month OJT	no
Deburring & Finishing	17	510	yes	mod	2-4 yr appr.	по
Plating	14	420	ves	high	4 yr appr. & OJ	T no
Heat Treating	11.5	345	yes	•	4 yr appr. & OJ	
AAA3XY	22222	NICIN	yes	high	4 yr appr.	yes
Totals						

Orher columnar data titles of interest might include the following: "Boring/
!titive", "Precision Required", "Product Design Complexity", Product Fragility",
.terial Cost", "Scrap Rate", "Part Size", "Part Weight", "Support Equipment
Maint. Cost", "Skilled Labor Availability", "Unit Product Volume/yr", "Process
Environment", etc.

Process: Plating



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SAMPLE SUPERTY ANALYSIS OF PREVIOUS SEQUENCE

Package. Ship Parts	0.75 m-hre
Assemble	1.2 m-hre
Clean, Inspect Parts	1.75 m-hre
Load, Plate Parts	2.00 m-hre
Machine, Grind Parts	2.63 m-hrs
sduct, Dissessable	2.55 m-bra

TAILED PROCESS SEQUENCE:

Cleaning, inspecting, handling: 60¢ Machining, grinding, handling: Plating, handling: 70¢ Disassembly, handling: 80¢ erage loads /day: 4.9 et/load (@\$30/m-hr): \$326.40 tal labor cost/yr.: \$420,000 tal labor bours/yr.: 14,000 tal parte loads /yr: 1,287 1. Labor cost/part: \$3.60 < tal man-bours: 10.88/load jection rate: 10% rte /load: 100

Assembly: 40c Packaging and shipping: 30c

SAMPLE ROBOTICS PROJECT SUMMARY INFORMATION MATRIX

Activity: Aircraft Depot XYZ

:oject	Date	Project Mgr.	Cost	Process Automates	ECD	Misc.
Automated Tail Bender	FY 82	Jay Endeffector	240	Straighten P&U Tails	6/84	Utilises Laser Holograp Vision System
Robotic Tire Tester	FY 83	Lionel Gripper	330	Auto Test and handle Guy Rubber Tires	9/85	Multi-arm Robot Bounce- Tests Tires
Small Parts Fetch	FY 84	Fred Tactile	150	Walking Robot Inter- Facing with Small Parts Bin-dump	1/85	Aircraft Small Parts on Prod. Floor. Voice Programmable
Apprentice Chute Trainer	FY 81	Geronimo R2D2	230	Robot Packs and Tests Parachutes	Comp.	Chute Redesign to accommodate robot pack

The object here is to provide a quick compressed summary of robotics projects in execution, completed, and planned. This is only a sample summary. Other columnar headings which might be relevant include: "Unique Features", "Special Problems", "Payback Period", "Type of Installation" (i.e. stand alone, system integration, etc.), "Software Language", etc., etc.

AGENDA

DOD ROBOTICS APPLICATION WORKSHOP

Sierra Inn, Sacramento, CA

Redwood Ballroom

MONDAY, 3 Oct 83		
1600 - 2000	Registration	Sierra Inn Pecan Room
TUESDAY, 4 Oct 83		
0700 - 0900	Registration	Sierra Inn, Room 151
0800 - 0810	Welcome	3rig Gen T.A. Hammond Vice Commander, Sacramento Air Logistics Center
0810 - 0815	Workshop Administrative Details	W. Walden, SM-ALC
0815 - 0825	Introduction	J. Sullivan, IBEA
	OVERVIEW OF THE STATE-OF-THE-ART IN ROBOTICS AND APPLICATION ASSESSMENT SESSION	•
	Moderator: Dr K. McKee, Manufacturing Productivity Center	
0830 - 0850	Robot implementations and associated benefits	V. Estes, General Electric Co.
0850 - 0910	Current robot applications and direction of research	D. Anderson, Ford Motor Co.
0910 - 0930	Robot system experiences, successes and failures	R.M. Hills, General Dynamics Corp.
0930 - 0950	Robot systems performance and capabilities	R. Hinson, Robot Systems Inc.
0950 - 1010	Overall analysis of current robot systems	R. Hohn, Cincinnati Milacron
1010 - 1025	Break	
1025 - 1045	State-of-the-art in applied research and its direction	Dr R. Nagel, Lehigh University

1045 - 1105	Robot technology and human factors	J.E. Taylor, HumaRRO
1105 - 1125 -	General issues for manufacturing policy - balance for RgD	Dr D. Tesar, University of Florida
1125 - 1145	Current successful robot applications	G. VanderBrug, Automatix Inc.
1145 - 1205	Robot welding systems	J. Fouse, Vought Corp.
1205 - 1225	The future - What does the next decade hold?	M. Knasel, Science Applications Inc.
1225 - 1345	Lunch	
	DEPOT PROCESS REVIEW SESSION	
	Moderator: F. Gale, Defense Systems Manage- ment College	
1345 - 1400	Air Force Aircraft Repair	G. Langenbeck, SM-ALC/MAB
1400 - 1415	Air Force Engine Repair	M. LeBlanc, OC-ALC/MAE
1415 - 1430	Air Force Electronics Repair	W. Ramsey, WR-ALC/MAI
1430 - 1445	Air Force Landing Gear Repair	Lt Col Hruskocy. OO-ALC/MAN
1445 - 1455	Navy Depot processes	NARF Alameda
1455 - 1505	Navy Depot processes	NARF Cherry Point
1505 - 1515	Navy Depot processes	NARF Jacksonville
1515 - 1525	Navy Depot processes	NARF Norfolk
1525 - 1535	Navy Depot processes	NARP North Island
1535 - 1545	Navy Depot processes	NARF Pensacola
1545 - 1600	Break	
1600 - 1700	Navy Shipyard processes	NSY Charleston NSY Long Beach NSY Mare Island NSY Norfolk NSY Pearl Harbor NSY Philadelphia NSY Portsmouth NSY Puget Sound

Action of the second

1700 - 1720	Question/Answer and Discussion	
1720	Adjourn	
1720 - 1735	Roundtable Leaders Meeting	Location to be announced.
1830 - 2030	No Host Social Hour	Redwood A Room
2030 - 2200	Evening program, to be announced.	Pecan and Sequoia Rooms
WEDNESDAY, 5 Oct 83		
	DEPOT PROCESS REVIEW SESSION - CONTINUED	
	Moderator: J. Sullivan, IBEA	
0800 - 0820	Exploration & analysis of process sequences	J. Nitterhouse, Letterkenny Army Depot
0820 - 0830	Current operation and economics of welding, plating, painting and wan assembly	E. Helalian, Sacramento Army Depot
0830 - 0845	Combat vehicle track and suspension overhaul and conversion operations	W. Costerveen. Red River Army Depot
0845 - 0900	Overhaul of communications - electronic shelters	F. Estock, Tobyhanna Army Depot
0 900 - 0 9 15	Use of robotics in material handling of hazardous materials	F. Eldriege, Tooele Army Depot
0915 - 1000	Navy Weapon Stations Ordnance Depots "" "" "" "" "" "" "" ""	NWS Charleston NWS Concord NWSC Crane NWS Earle NOS Indian Head NUWES Keyport NOS Louisville NWS Seal Beach NWS Yorktown
1000 - 1015	CURRENT DEPOT ROBOTICS PROJECTS SESSION Moderator: L. Hary, AFLC/MAXT	
1015 - 1025	Air Force, Blade Repair	M. LeBlanc, OC-ALC/MAE

1025 - 1035	Air Force, Plasma Spray at SA-ALC	S. Lee, AFWAL/MLTM
1035 - 1045 .	Air Force, Honeycomb Shaping at SM-ALC	G. Betz, Robotic Vision
1045 - 1055	Air Force, Robotic Painting	Col R. Grabler, OO-ALC/MAW
1055 - 1120	Navy Robotics projects	narps
1120 - 1130	Navy Robotics projects	YARDS
1130 - 1135	Navy Robotics projects	nws/nos
1135 - 1145	Neo-robotic application development	J. Nitterhouse, Letterkenny Army Depot
1145 - 1155	Feasibility and economic considerations of robotic applications at welding shop	E. Helalian, Sacramento Army Depot
1155 - 1205	Robotic applications to combat vehicle track and suspension over-haul and conversion operations	W. Oosterveen, Red River Army Depot
1205 - 1215	Application of robotics to shelter refinishing	S. O'Malley. Tobyhanna Army Depot
1215 - 1325	POTENTIAL DEPOT APPLICATIONS AND PLANS FOR THE FUTURE	
	Moderator: J. Sullivan, IBEA	
1335 - 1345	DLA Depot Automation	Col T. Kirkham, Defense Logistics Agency
1345 - 1355	Laser Paint Removal	T. Mallets, AFLC/MAXT
1355 - 1405	Air Force Materials Laboratory Plans/Projects	S. Lee, AFWAL/MLTM
1405 - 1415	AIM Industry/Depot Survey	P. Brooks, AFSC/PMI
1415 - 1425	OO-ALC plans	Col R. Grabler, CO-ALC/MAW
1425 - 1435	SA-ALC plans	Lt Col J. Ferry, SA-ALC/MAW

1435 - 1445	Robotics in NDI, SM-ALC	D. Froom, SM-ALC/MAM
1445 - 1500	Navy plans	NARTS
1500 - 1515	Navy plans	Shipyards
1515 - 1530	Break	
1530 - 1545	Navy plans	nws/nos
1545 - 1600	Navy plans	NCS San Diego/ NAVSUPHQ PWC/NAVFACHQ
1600 - 1610	Robotic systems for camouflage painting, welding, laser engraving and the integration of state-of-the-art end effectors to planned systems.	J. Nitterhouse, Letterkenny Army Depot
1610 - 1625	Engineering and economic consider- ations of potential robotic applications	E. Helalian, Sacramento Army Depot
1625 - 1635	Robotic camouflage painting of the M113 vehicle family	W. Oosterveen, Red River Army Depot
1635 - 1700	Field applications for robotic material handling systems	C. Shoemaker, Human Engineering Laboratory, and F. Eldriege, Tooele Army Depot
1700 - 1730	Questions & Answers	
1730	Adjourn	
2030 - 2200	Evening program, to be announced.	Pecan and Sequoia Rooms

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THURDAY, 6 Oct 83

or

0800 - 1600

ROUNDTABLE SESSIONS

Locations to be posted.

BOCECTORS to be poster.	
Moderator: P. Gale, Defense Systems Management College	
Simultaneous Roundtables - Session 1 (see attachment for topics and leaders)	Government & Industry
Simultaneous Roundtables - Session 2 (see attachment for topics and leaders)	Government & Industry
Break	
Simultaneous Roundtables - Session 3 (see attachment for topics and leaders)	Government & Industry
Lunch	
Roundtable Summary Presentations (10 each, 13 min presentations)	Chairpersons
Break	
Open Discussion & Wrap-up Summary	J. Sullivan, IBEA
Adjourn	
Tour of SM-ALC Production Operations (Optional)	
	Moderator: F. Gale, Defense Systems Management College Simultaneous Roundtables - Session 1 (see attachment for topics and leaders) Simultaneous Roundtables - Session 2 (see attachment for topics and leaders) Break Simultaneous Roundtables - Session 3 (see attachment for topics and leaders) Lunch Roundtable Summary Presentations (10 each, 13 min presentations) Break Open Discussion & Wrap-up Summary Adjourn Tour of SM-ALC Production Operations

NOTE: Registration/reception desk will be open on Monday, 3 October from 1600 - 2000 in Pecan Room, Sierra Inn. The desk will be open in Room 151 from 0700 - 0900 on Tuesday, 4 October to accommodate late arrivals.

Robotic Conference at California State University, (Optional -- See Flyer: "Towards Intelligent Robots.")

DOD ROBOTICS APPLICATION WORKSHOP

ROUNDTABLE SESSIONS

Moderator: P. Gele, Defense Systems Management College

	Roundtable Topics	Leaders
1.	Potential Applications	V.E. Estes, General Electric Co. D. Anderson (co-leader), Ford Motor Co.
2.	Robot Installation/Design Concepts	R. Hinson, Robot Systems Inc.
3.	Robot Safety/Security	R. Hohn, Cincinnati Milacron
4,	Robot Language Concepts/Development	Dr R. Nagel, Lehigh University
5.	Robot Mechanical Systems/Precision Operations	Dr D. Tesar, University of Florida
6.	Robot Vision	G. Bets, Robotic Vision Systems Inc.
7.	Robot Control and Integrated Systems	J. Evans, Nova Robotics Inc.
8.	Robot Hands and End Effectors	R. Hills, General Dynamics Corp.
9.	Topic to be Announced	G. VanderBrug, Automatix Inc.
10.	Robot Transportability/Mobility	M. Knasel, Science Applications Inc.

DOD ROBOTICS APPLICATIONS WORKSHOP ATTENDEES

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